

谭森
Sean Stein

美中贸易全国委员会会长

President of the US-China Business Council

在加入美中贸易全国委员会之前，谭森曾担任中国美国商会董事会主席和上海美国商会的名誉主席。他还曾作为科文顿·柏灵律师事务所中国公共政策业务组的联席主席，为国际企业提供政治风险、公共事务、传播以及中美政府关系方面的咨询。他经常为企业提供支持，协助其妥善应对在华运营中出现的突发或长期问题，以及因中美政策冲突和认知差异带来的各类挑战。

此前，谭森担任美国外交官近三十年，曾任美国驻沈阳和上海总领事。他还曾在美国国务院中国事务协调办公室，前美国驻成都总领事馆及亚太地区的多个国家担任职务。谭森精通中文和印尼语，毕业于美国乔治敦大学。

He most recently served as the board chair of the American Chamber of Commerce in China and is the chair emeritus of the American Chamber of Commerce in Shanghai. He also co-chaired the China Public Policy Practice at Covington and Burling where he advised international businesses on political risk, public affairs, communications, and US and China government relations. He regularly assisted companies in resolving acute or long-term issues in China and in navigating challenges caused by conflicting US and Chinese policies and perceptions.

Sean previously served for nearly three decades as a US diplomat, including as Consul General in Shenyang and Shanghai. He also served on the China desk at the State Department, at the former consulate general in Chengdu, and in other positions around the Indo-Pacific. Sean speaks Mandarin and Indonesian and is a graduate of Georgetown University.



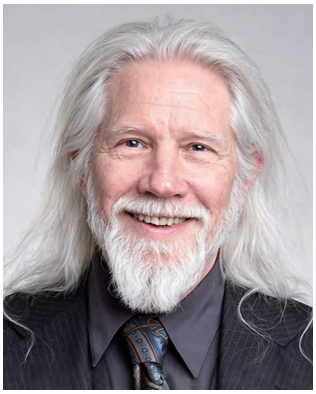
王兴兴
WANG Xingxing

宇树科技股份有限公司创始人、董事长

Founder and Chairman of Unitree Robotics Co., Ltd.

科技至上主义者。在硕士研究生期间全球范围内开创性的开发了使用低成本外转子无刷电机驱动的高运动性能小型四足机器人XDog。2016年宇树科技（Unitree Robotics）成立，在全球率先公开零售高性能四足机器人，全球销量领先，显著推动了全球高性能四足机器人的市场化进程。曾受邀参加ICRA2018-2022足式机器人论坛演讲等国际顶级机器人会议，带领团队累计申请国内外专利200余项，带领公司产品登上央视牛年春晚、美国超级碗等顶级舞台。

A firm believer in technocentrism. During his master's studies, he pioneered the development of XDog, a high-performance small quadruped robot driven by low-cost outrunner brushless motors, gaining worldwide recognition. Founded in 2016, Unitree Robotics became the first company to publicly retail high-performance quadruped robots globally, leading in global sales and significantly advancing the commercialization of high-performance quadruped robots worldwide. He has been invited to speak at top international robot conferences, including ICRA 2018-2022 Legged Robot Forums. Under his leadership, the team has accumulated over 200 domestic and international patent applications. Unitree Robotics' s products have been featured on top stages, such as the 2021 China Media Group Spring Festival Gala Evening and the US Super Bowl.



惠特菲尔德·迪菲
Whitfield Diffie

2015年图灵奖得主、
美国国家工程院院士

2015 Turing Award Laureate, Member of the US National Academy of Engineering (NAE)

惠特菲尔德·迪菲教授是2015年图灵奖获得者，他与马丁·赫尔曼教授共同获奖，以表彰他们对公钥密码学的开创性贡献。

迪菲教授被广泛认为是现代密码学的先驱之一。20世纪70年代，他与马丁·赫尔曼共同推动发展了公钥密码学。这是一种革命性的方法，使个人和组织无需事先共享秘密加密密钥，就能安全地交换信息。其研究成果为当今网上银行、电子商务和安全数字通信中使用的许多安全技术奠定了基础。他们还帮助确立了数字签名的概念，使接收方能够验证电子文档的真实性和完整性。除技术成就外，迪菲教授还一直是数字隐私和负责任使用加密技术的积极倡导者，为有关网络安全、政府监控和个人隐私保护的国际讨论作出了贡献。

Professor Whitfield Diffie is a recipient of the 2015 Turing Award, which he shared with Professor Martin Hellman for their pioneering contributions to public-key cryptography. Professor Diffie is widely recognized as one of the pioneers of modern cryptography. In the 1970s, he and Martin Hellman helped develop public-key cryptography, a revolutionary approach that allows people and organizations to exchange information securely without first having to share a secret encryption key. Their work laid the foundations for many of the security technologies used in online banking, e-commerce and secure digital communications today. They also helped establish the concept of digital signatures, which enable recipients to verify the authenticity and integrity of electronic documents. Beyond his technical achievements, Professor Diffie has been a prominent advocate for digital privacy and the responsible use of encryption, contributing to international debates on cybersecurity, government surveillance and the protection of individual privacy.



高继扬
GAO Jiyang

星海图人工智能科技股份有限公司创始人、首席执行官

Founder and CEO of Galaxea/Xinghaitu AI Technology Co., Ltd.

一位在具身智能领域兼具顶尖科研底蕴与商业落地能力的领军者。他本科毕业于清华大学电子工程系（2011级），仅用3.5年便获得美国南加州大学计算机视觉博士学位，累计发表顶级会议论文20余篇，Google Scholar引用超过6,000次。

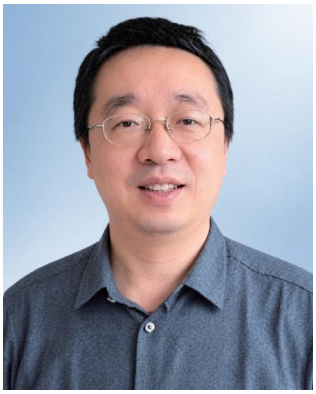
2023年9月，创立星海图，确立“整机+智能”的战略方向，专注于具身智能基础模型与具身智能机器人的自主研发。目前，星海图商业化进程迅速领跑行业，已服务全球数百家顶尖具身智能客户。公司坚持开放利他的发展理念，带领星海图构建具身智能应用生态，推动技术从实验室走向真实场景、走向千家万户。

高继扬于2026年1月受聘工信部人形机器人与具身智能标准化技术委员会委员，并入选2025年“中国AI产业先锋CEOTOP30”及“40岁以下最具潜力商界精英”榜单，入选EAI Pioneer 20具身智能先锋任务榜单。

A leading figure in the embodied intelligence sector with both world-class research credentials and a proven track record of commercial deployment. He earned his bachelor’ s degree from the Department of Electronic Engineering at Tsinghua University (enrolled in 2011), and completed his PhD in Computer Vision at the University of Southern California in just 3.5 years. To date, he has published over 20 papers at top-tier AI academic conferences, with cumulative citations exceeding 6,000 on Google Scholar.

In September 2023, he founded Xinghaitu and defined the company’ s strategic direction of "complete robot systems + AI intelligence", focusing on proprietary R&D of embodied intelligence foundation models and embodied intelligent robots. Xinghaitu has rapidly emerged as an industry front-runner in commercialization, now serving hundreds of leading embodied intelligence clients worldwide. Guided by an open and ecosystem-enabling development philosophy, he leads the company in building a robust application ecosystem for embodied intelligence, advancing the translation of laboratory technologies into real-world scenarios and mass-market adoption.

In January 2026, he was appointed as a member of the Technical Committee on Standardization of Humanoid Robots and Embodied Intelligence under the Ministry of Industry and Information Technology (MIIT) of China. He was also honored on the 2025 China AI Industry Pioneer CEO Top 30 list and the 40 Under 40 Most Promising Business Leaders list, and was selected for the EAI Pioneer 20 Embodied Intelligence Trailblazers roster.



任雷
REN Lei

吉林大学唐敖庆杰出教授、
国际仿生工程学会常务副理事长、
月泉仿生科技创始人

Tang Aoqing Distinguished Professor of Jilin University;
Executive Vice President of the International Society of
Bionic Engineering (ISBE); and founder of YQ Bionics

英国曼彻斯特大学教授(回国前)，现为国家特聘专家、教育部重大人才工程讲座教授、吉林大学唐敖庆卓越教授、仿生机器人与仿生健康学科带头人、吉林省仿生机器人创新中心主任。现任国际仿生工程学会(ISBE)常务副理事长、国际生物医学工程学会(BMES)理事及英国区域主席、国际机构学与机器科学联合会(IFToMM)英国区秘书长。长期从事仿生机器人和人体科学研究，主要采用多领域交叉学科的方法研究人体骨骼肌肉系统和运动神经系统的基本规律和工作机理，结合先进功能材料、先进制造技术和人工智能技术，开发新型仿生机器人、仿生驱动器和传感器、仿生健康器械与装备等，取得了一系列原创性成果。开拓了基于骨骼肌肉智能的仿生机器人领域，国际首创了仿生拉压体机器人理论与技术。

Professor at the University of Manchester, UK (before returning to China), he is currently a National Distinguished Expert, a Chair Professor under the Major Talent Program of the Ministry of Education, a Tang Aoqing Distinguished Professor at Jilin University, an academic leader in Bionic Robotics and Bionic Health, and Director of the Jilin Provincial Bionic Robot Innovation Center. He currently serves as Executive Vice Chairman of the International Society of Bionic Engineering (ISBE), Council Member and UK Regional Chair of the Biomedical Engineering Society (BMES), and Secretary-General of the UK Branch of the International Federation for the Promotion of Mechanism and Machine Science (IFToMM). He has long been engaged in research on bionic robotics and human body science. He mainly adopts multidisciplinary and interdisciplinary approaches to study the fundamental principles and operating mechanisms of the human musculoskeletal system and motor nervous system, and combines advanced functional materials, advanced manufacturing technologies, and artificial intelligence technologies to develop novel bionic robots, bionic actuators and sensors, and bionic health devices and equipment, achieving a series of original results. He pioneered the field of bionic robotics based on musculoskeletal intelligence and was the first internationally to propose the theory and technology of bionic tension-compression body robots.



孟樸
Frank Meng

高通公司中国区董事长

Chairman of Qualcomm China

现任高通公司中国区董事长，全面负责高通在中国的业务和运营，包括执行公司战略和推动业务增长，进一步加强高通公司与中国无线通信及半导体产业的合作。

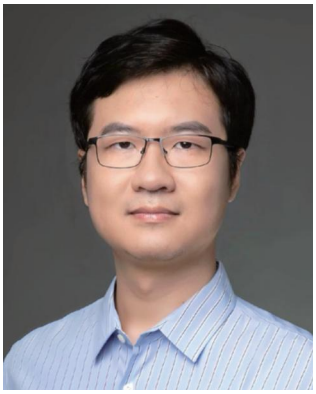
在电信行业拥有30年的丰富经验，之前他曾在高通公司就职8年，于2003年到2010年期间担任高通中国区总裁。此前，孟樸一直担任世纪互联总裁，负责战略规划、品牌和市场营销、政府事务以及战略项目。加入世纪互联之前，他曾任摩托罗拉移动高级副总裁兼大中华区总裁。

拥有北京邮电大学微波和光通讯专业的电子工程学学士学位，以及纽约理工大学通讯系统专业的电子工程学硕士学位。

Frank Meng serves as chairman of Qualcomm China and is responsible for overseeing the overall Qualcomm' s business and operations in China, including executing on the strategic initiatives of the Company and driving business growth, as well as further strengthening Qualcomm' s collaborations with the Chinese wireless communications ecosystem and the semiconductor industry.

Frank has 30 years of telecommunications experience, eight of those with Qualcomm, which included serving as president of Qualcomm China from 2003 to 2010. Most recently, Frank was President of 21Vianet Group in Beijing, where he was responsible for strategic planning, branding and marketing, government affairs and strategic initiatives. Prior to 21Vianet Group, he was with Motorola Mobility in Beijing where he served as senior vice president and president of Greater China .

Frank holds a bachelor' s degree of science in Microwave and Fiber Optic Communications from Beijing University of Posts and Telecommunications, and a master' s degree of science in Electrical Engineering from the Polytechnic University of New York.



王潜
WANG Qian

自变量机器人公司创始人、首席执行官

Founder and CEO, X Square Robot Technology Co., Ltd.

自变量机器人创始人兼CEO，本硕士毕业于清华大学，南加州大学读博期间，在美国顶级机器人实验室从事机器人学习与人机交互研究，是全球最早在神经网络中提出Attention机制的研究者之一。2023 年回国创立自变量机器人，团队致力于研发由端到端大模型驱动的通用机器人，聚焦具身大模型的通用性与泛化能力，2026年发布全球首个世界统一模型，并自主研发、持续优化原生适配具身模型控制的机器人本体，长远目标是构建能够精细操作的通用智能机器人。

He earned his bachelor's and master's degrees from Tsinghua University. During his doctoral studies at the University of Southern California, he conducted research on robot learning and human-robot interaction at a premier U.S. robotics laboratory, and is among the earliest researchers worldwide to propose the attention mechanism for neural networks. He returned to China in 2023 to found X Square Robot. The team is dedicated to building general-purpose robots powered by end-to-end large foundation models, with a core focus on the generality and generalization capabilities of embodied foundation models. In 2026, the company launched the world's first unified world model, and has independently developed and continuously optimized robot platforms natively engineered for embodied model-driven control. Its long-term vision is to create general intelligent robots capable of dexterous manipulation.



席宁
XI Ning

中国电子学会机器人分会主任委员、
香港大学机器人与自动化讲座教授及系主任、
新兴技术研究所所长

Chairman of the Robotics Branch, Chinese Institute of Electronics; Chair Professor & Head of Department of Robotics and Automation, and Director of the Institute of Emerging Technologies, The University of Hong Kong

毕业于美国密苏里州圣刘易斯华盛顿大学，持有系统科学与数学博士学位。现任香港大学机器人与自动化讲座教授及系主任，及香港大学新兴技术研究所所长。加入香港大学之前，他曾任美国密歇根州立大学机电与计算机工程系John D. Ryder教授，机器人与自动化实验室主任。

席教授是IEEE Fellow，曾任IEEE纳米技术理事会主席(2010-2011)，IEEE机器人及自动化学会主席（2018）。研究领域包括机器人、制造自动化、微/纳米制造、纳米传感器和设备以及智能控制和系统。

He received his Doctor of Philosophy degree in Systems Science and Mathematics from Washington University in St. Louis, Missouri, USA. He currently serves as Chair Professor and Head of the Department of Robotics and Automation, as well as Director of the Institute of Emerging Technologies at the University of Hong Kong. Prior to joining the University of Hong Kong, he held the John D. Ryder Professorship in Electrical and Computer Engineering and served as Director of the Robotics and Automation Laboratory at Michigan State University, USA.

Professor Xi is an IEEE Fellow. He previously chaired the IEEE Nanotechnology Council (2010–2011) and served as President of the IEEE Robotics and Automation Society (2018). His research interests cover robotics, manufacturing automation, micro/nano manufacturing, nanosensors and devices, as well as intelligent control and systems.



江磊
JIANG Lei

国家地方共建人形机器人创新中心首席科学家

Chief Scientist, National-Local Co-built Humanoid Robotics Innovation Center

国地共建人形机器人创新中心首席科学家，科技部“智能机器人”专项总体组专家、国自然“共融机器人”秘书组成员，长期致力于人形机器人、四足机器人、智能仿生行走等技术研究，主导开展了“青龙”人形机器人、350kg电动牦牛、月面移动机器人FDTM等项目，正在主导开展人形机器人开源社区OpenLoong，发布“格物”开源具身智能仿真平台，7B参数的“龙跃”运动生成大模型。获得省部级科技进步奖5项，发布论文30余篇，专利50余项。

Chief Scientist of the National and Local Joint Innovation Center for Humanoid Robots, expert of the Overall Group of the "Intelligent Robots" special project of the Ministry of Science and Technology, and member of the Secretariat of the "Collaborative Robots" of the National Natural Science Foundation of China, he has long been committed to the research on technologies such as humanoid robots, quadruped robots, and intelligent bionic walking. He has led the development of projects including the "Qinglong" humanoid robot, 350kg electric yaks, and the lunar mobile robot FDTM. Currently, he is leading the development of the humanoid robot open source community OpenLoong, and has released the "Ge Wu" open-source embodied intelligence simulation platform and the "Long Yue" motion generation large model with 7B parameters. He has won 5 provincial and ministerial-level Science and Tech Progress Awards, published more than 30 papers, and held over 50 patents.



石选阳
SHI Xuanyang

星动纪元董事长

Chairman of ROBOTERA

北京星动纪元科技股份有限公司董事长，技术负责人。长期从事具身机器人研究，覆盖人形机器人运动控制、灵巧操作、具身应用等多个方向。北京理工大学博士，研究方向为人形机器人运动控制与灵巧操作算法，曾获胡润U30中国创业先锋奖。

Chairman of the Board & Technical Lead, Beijing ROBOTERA Corporation. He has long been engaged in embodied robotics research. His work spans humanoid robot motion control, dexterous manipulation, and embodied robotics applications. He holds a PhD from Beijing Institute of Technology, where his doctoral research focused on motion control and dexterous manipulation algorithms for humanoid robots. He was named to the Hurun China Under30s list.



王东
WANG Dong

摩尔线程联合创始人、执行总裁

Co-founder and Executive President of Moore Threads

拥有多年芯片行业市场与销售管理经验。2020年联合创立摩尔线程，先后担任监事、董事会秘书，现任副总经理。长期负责公司市场、生态与产业合作，推动国产MUSA全功能GPU智算集群落地，拓展AI算力生态，助力摩尔线程构建芯片、板卡、集群与软件全栈产品体系。

He has years of experience in marketing and sales management within the chip industry. He co-founded Moore Threads in 2020 and has served successively as Supervisor and Secretary of the Board of Directors, currently holding the position of Deputy General Manager. He has long been in charge of the company's marketing, ecosystem and industrial cooperation. He promotes the implementation of domestic MUSA full-function GPU computing clusters, expands the AI computing ecosystem, and helps Moore Threads build a full-stack product system covering chips, boards, clusters and software.



冷晓琨
LENG Xiaokun

乐聚机器人董事长

Chairman of Leju Robotics

冷晓琨，乐聚机器人董事长，哈尔滨工业大学研究员，国家科技专家库专家、中国电子学会机器人分会副主任、全国青联委员、黑龙江省青联副主席、广东省科协常委、广东省青科协常务副会长，深圳市“十五五”规划专家委员会专家。主要聚焦双足人形机器人及人工智能领域进行关键技术研究与产品研发制造。曾获中国青年五四奖章、中国青年创业奖、中国青少年科技创新奖、工信部创新创业特等奖、吴文俊人工智能科学技术奖“科技进步奖”、深圳市青年科技奖等荣誉，并两次入选福布斯“30位30岁以下精英榜”。

He is Chairman of Leju Robotics, Researcher at Harbin Institute of Technology (HIT), an expert in the National Science and Technology Expert Database, Vice Chairman of the Robotics Branch of the Chinese Institute of Electronics, member of the All-China Youth Federation (ACYF), Vice Chairman of the Heilongjiang Provincial Youth Federation, Standing Committee Member of the Guangdong Provincial Association for Science and Technology, Executive Vice President of the Guangdong Youth Association for Science and Technology, and an expert on the Expert Committee for Shenzhen's 15th Five-Year Plan.

His core work focuses on key technology research and product R&D and manufacturing in the fields of biped humanoid robots and artificial intelligence.

He has received numerous honors including the China Youth May Fourth Medal, China Youth Entrepreneurship Award, China Youth Science and Technology Innovation Award, Special Award for Innovation and Entrepreneurship from the Ministry of Industry and Information Technology (MIIT), the Wu Wenjun Artificial Intelligence Science and Technology Progress Award, and the Shenzhen Youth Science and Technology Award. He has also been named on the Forbes 30 Under 30 list twice.